

```
<?
/***
 * @file modbus.inc
 * @author Akash Heimlich
 * @version 1.0
 * @date 09/04/2021
 * @description Modbus functions
 */

define('MB_ILLEGAL_FUNCTION', -1);
define('MB_ILLEGAL_ADDRESS', -2);
define('MB_ILLEGAL_VALUE', -3);
define('MB_SLAVE_FAILURE', -4);

/***
 * mb_get_error_string - get modbus exception error
 *
 * Return a human readable error string based on the exception code
 *
 * @param int $error_number - Modbus except (negative value)
 *           For exceptions not generated by the functions in this library,
send it as -$error_number
 * @return string Human readable description of the error
 */
function mb_get_error_string($error_number) {

    if ($error_number==MB_ILLEGAL_FUNCTION) {
        return "Illegal Modbus Function";
    }
    if ($error_number==MB_ILLEGAL_ADDRESS) {
        return "Illegal Modbus Register Address";
    }
    if ($error_number==MB_ILLEGAL_VALUE) {
        return "Illegal Modbus Value";
    }
    if ($error_number==MB_SLAVE_FAILURE) {
        return "Device Slave Failure";
    }
    return "";
}

/***
 * mb_set_int16_0x03 - set 16-bit register via function 03
 *
 * Set a modbus register using function code 03
 *
 * @param int $id - Modbus device ID
 * @param int $bus - Modbus bus ID (0 for Rs-485, 1 for RS-482 2, 2-11 for
TCP channels 0-10)
 * @param int $reg - Register ID
 * @param int $cmd - Value
 */
```

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* @param int $id - Modbus device ID
*
* @return int 0 for failure, < 0 if modbus exception, 1 if successful
*/

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```
function mb_set_int16_0x03($id, $bus, $reg, $cmd, $retries)
{
    print("/scripts/tests/modbus.inc");
    global $DEBUG;
    $base_addr = $reg;
    $num_bytes = 2;
    $msg = array(
        $id,
        6
    );
    $msg[] = $base_addr >> 8;
    $msg[] = $base_addr & 0xFF;
    $msg[] = $cmd >> 8;
    $msg[] = $cmd & 0xFF;
    if ($DEBUG) {
        print ("<span class='info'>[MODBUS]</span>\r\nSet register -
Retries=" . $retries);
    }
    $res = 0;
    while ($retries) {
        $res = mb_send_command($bus, $msg);
        $retries--;
        if (is_array($res) && sizeof($res)) {
            break;
        }
        if ($DEBUG) {
            print("\r\n<span style='color:red'>Modbus Command
FAILED</span>\r\n");
        }
    }

    if (is_array($res)) {
        // if the result was successful
        if ($res[1]==6) {
            return 1;
        } else return -$res[2]; // return modbus exception code
    }
    return $res;
}

/**
 * mb_set_int16_0x10 - set 16-bit register via function 10h
 *
 * Set a modbus register using function code 10h
 *
 * @param int $id - Modbus device ID

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 * @param int $bus - Modbus bus ID (0 for Rs-485, 1 for RS-482 2, 2-11 for
TCP channels 0-10)
 * @param int $reg - Register ID
 * @param int $cmd - Value
 * @param uint $retries - number of retries
 *
 * @return int 0 for failure, < 0 if modbus exception, 1 if successful
*/

```

```

function mb_set_int16_0x10($id, $bus, $reg, $cmd, $retries)
{
    global $DEBUG;
    $base_addr = $reg;
    $num_bytes = 2;
    $msg = array(
        $id,
        0x10
    );
    $msg[] = $base_addr >> 8;
    $msg[] = $base_addr & 0xFF;
    $msg[] = 0;
    $msg[] = 1;
    $msg[] = 2;
    $msg[] = $cmd >> 8;
    $msg[] = $cmd & 0xFF;
    $res=0;
    while ($retries) {
        $res = mb_send_command($bus, $msg);
        $retries--;
        if (is_array($res) && sizeof($res)) {
            break;
        }
        if ($DEBUG) {
            print("\r\n<span style='color:red'>Modbus Command
FAILED</span>\r\n");
        }
    }
    if (is_array($res)) {
        // if the result was successful
        if ($res[1]==0x10) {
            return 1;
        } else return -$res[2]; // return modbus exception code
    }
    return $res;
}

/**
 * mb_set_uint32_be_0x10 - set 32-bit uint big endian via function 10h
 *
 * Set a big endian UINT32 register via function 0x10h

```

```
*  
* @param int $id - Modbus device ID  
* @param int $bus - Modbus bus ID (0 for Rs-485, 1 for RS-482 2, 2-11 for  
TCP channels 0-10)  
* @param int $reg - Register ID  
* @param int $cmd - Value  
* @param int $retries - number of retries  
*  
* @return int 0 for failure, < 0 if modbus exception, 1 if successful  
*/  
function mb_set_uint32_be_0x10($id, $bus, $reg, $cmd, $retries)  
{  
    global $DEBUG;  
    $base_addr = $reg;  
    $num_bytes = 4;  
    $msg = array(  
        $id,  
        0x10  
    );  
    $msg[] = $base_addr >> 8;  
    $msg[] = $base_addr & 0xFF;  
    $msg[] = 0;  
    $msg[] = 2;  
    $msg[] = 4;  
    $msg[] = $cmd >> 24 & 0xFF;  
    $msg[] = $cmd >> 16 & 0xFF;  
    $msg[] = $cmd >> 8 & 0xFF;  
    $msg[] = $cmd & 0xFF;  
    $res=0;  
    while ($retries) {  
        $res = mb_send_command($bus, $msg);  
        $retries--;  
        if (is_array($res) && sizeof($res)) {  
            // print_r($res);  
            break;  
        }  
        if ($DEBUG) {  
            print("\r\nFAILED</span>\r\n");  
        }  
  
        //print_r($res);  
    }  
    if (is_array($res)) {  
        // if the result was successful  
        if ($res[1]==0x10) {  
            return 1;  
        } else return -$res[2]; // return modbus exception code  
    }  
    return $res;  
}
```

```
/**  
 * mb_set_uint32_le_0x10 - set 32-bit uint little endian via function 10h  
 *  
 * Set a little endian UINT32 register via function 0x10h  
 *  
 * @param int $id - Modbus device ID  
 * @param int $bus - Modbus bus ID (0 for Rs-485, 1 for RS-482 2, 2-11 for  
TCP channels 0-10)  
 * @param int $reg - Register ID  
 * @param int $cmd - Value  
 * @param int $retries - number of retries  
 *  
 * @return int 0 for failure, < 0 if modbus exception, 1 if successful  
 */  
function mb_set_uint32_le_0x10($id, $bus, $reg, $cmd, $retries)  
{  
    global $DEBUG;  
    $base_addr = $reg;  
    $num_bytes = 4;  
    $msg = array(  
        $id,  
        0x10  
    );  
    $msg[] = $base_addr >> 8;  
    $msg[] = $base_addr & 0xFF;  
    $msg[] = 0;  
    $msg[] = 2;  
    $msg[] = 4;  
    $msg[] = $cmd >> 8 & 0xFF;  
    $msg[] = $cmd & 0xFF;  
    $msg[] = $cmd >> 24 & 0xFF;  
    $msg[] = $cmd >> 16 & 0xFF;  
  
    $res=0;  
  
    while ($retries) {  
        $res = mb_send_command($bus, $msg);  
        $retries--;  
        if (is_array($res) && sizeof($res)) {  
            // print_r($res);  
            break;  
        }  
        if ($DEBUG) {  
            print("\r\n<span style='color:red'>Modbus Command  
FAILED</span>\r\n");  
        }  
  
        //print_r($res);  
    }  
    if (is_array($res)) {
```

```
// if the result was successful
if ($res[1]==0x10) {
    return 1;
} else return -$res[2]; // return modbus exception code
}

return $res;
}

/***
 * mb_set_float_be_0x10 - set 32-bit big endian float via function 10h
 *
 * Set a big endian float register via function 0x10h
 *
 * @param int $id - Modbus device ID
 * @param int $bus - Modbus bus ID (0 for Rs-485, 1 for RS-482 2, 2-11 for
TCP channels 0-10)
 * @param int $reg - Register ID
 * @param int $val - Value
 * @param int $retries - number of retries
 *
 * @return int 0 for failure, < 0 if modbus exception, 1 if successful
*/
function mb_set_float_be_0x10($id,$bus,$reg,$val,$retries) {
    global $DEBUG;
    $base_addr=$reg;
    $num_bytes=4;
    $msg=array($id,16);
    $msg[]=$base_addr >> 8;
    $msg[]=$base_addr & 0xFF;
    $msg[]=0;
    $msg[]=2;
    $msg[]=4;
    $val=floatval($val);
    $cmd = ieee754toint($val);

    $msg[]=$cmd >> 24 & 0xFF;
    $msg[]=$cmd >> 16 & 0xFF;

    $msg[]=$cmd >> 8 & 0xFF;
    $msg[]=$cmd & 0xFF;
    if ($DEBUG) {
        print("<span class='info'>[MODBUS]</span>\r\nSet Register Send:\r\n");
        print_r($msg);
        print ("Retries=" . $retries);
    }
    $res=0;
    while ($retries) {
        $res=mb_send_command($bus,$msg);
        $retries--;
    }
}
```

```
if (is_array($res) && sizeof($res)) {  
    break;  
}  
}  
  
if (is_array($res)) {  
    // if the result was successful  
    if ($res[1]==0x10) {  
        return 1;  
    } else return -$res[2]; // return modbus exception code  
}  
return $res;  
}  
  
/**  
 * mb_set_float_le_0x10 - set 32-bit little endian float via function 10h  
 *  
 * Set a little endian float register via function 0x10h  
 *  
 * @param int $id - Modbus device ID  
 * @param int $bus - Modbus bus ID (0 for Rs-485, 1 for RS-482 2, 2-11 for  
TCP channels 0-10)  
 * @param int $reg - Register ID  
 * @param int $val - Value  
 * @param int $retries - number of retries  
 *  
 * @return int 0 for failure, < 0 if modbus exception, 1 if successful  
 */  
function mb_set_float_le_0x10($id,$bus,$reg,$val,$retries) {  
    global $DEBUG;  
    $base_addr=$reg;  
    $num_bytes=4;  
    $msg=array($id,16);  
    $msg[]=$base_addr >> 8;  
    $msg[]=$base_addr & 0xFF;  
    $msg[]=0;  
    $msg[]=2;  
    $msg[]=4;  
    $val=floatval($val);  
    $cmd = ieee754toint($val);  
    $msg[]=$cmd >> 8 & 0xFF;  
    $msg[]=$cmd & 0xFF;  
  
    $msg[]=$cmd >> 24 & 0xFF;  
    $msg[]=$cmd >> 16 & 0xFF;  
  
    if ($DEBUG) {  
        print("<span class='info'>[MODBUS]</span>\r\nSet Register Send:\r\n");  
        print_r($msg);  
        print ("Retries=" . $retries);  
    }  
}
```

```
}

while ($retries) {
    $res=mb_send_command($bus,$msg);
    $retries--;
    if (is_array($res) && sizeof($res)) {

        break;
    }
}
if (is_array($res)) {
    // if the result was successful
    if ($res[1]==0x10) {
        return 1;
    } else return -$res[2]; // return modbus exception code
}
return $res;
}

?>
```

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